

Algebra

1. Laws of Exponents

$$a^m a^n = a^{m+n}, \quad (ab)^m = a^m b^m, \quad (a^m)^n = a^{mn}, \quad a^{m/n} = \sqrt[n]{a^m}$$

If $a \neq 0$,

$$\frac{a^m}{a^n} = a^{m-n}, \quad a^0 = 1, \quad a^{-m} = \frac{1}{a^m}.$$

2. Zero Division by zero is not defined.

$$\text{If } a \neq 0: \quad \frac{0}{a} = 0, \quad a^0 = 1, \quad 0^a = 0$$

For any number a : $a \cdot 0 = 0 \cdot a = 0$

3. Fractions

$$\frac{a}{b} + \frac{c}{d} = \frac{ad + bc}{bd}, \quad \frac{a}{b} \cdot \frac{c}{d} = \frac{ac}{bd}, \quad \frac{a/b}{c/d} = \frac{a}{b} \cdot \frac{d}{c}, \quad \frac{-a}{b} = -\frac{a}{b} = \frac{a}{-b}.$$

4. The Binomial Theorem For any positive integer n ,

$$(a + b)^n = a^n + na^{n-1}b + \frac{n(n-1)}{1 \cdot 2} a^{n-2}b^2 + \frac{n(n-1)(n-2)}{1 \cdot 2 \cdot 3} a^{n-3}b^3 + \cdots + nab^{n-1} + b^n.$$

5. Difference of Like Integer Powers, $n > 1$

$$a^n - b^n = (a - b)(a^{n-1} + a^{n-2}b + a^{n-3}b^2 + \cdots + ab^{n-2} + b^{n-1})$$

For instance,

$$a^2 - b^2 = (a - b)(a + b),$$

$$a^3 - b^3 = (a - b)(a^2 + ab + b^2),$$

$$a^4 - b^4 = (a - b)(a^3 + a^2b + ab^2 + b^3).$$

6. Completing the Square If $a \neq 0$,

$$\begin{aligned} ax^2 + bx + c &= a \left(x^2 + \frac{b}{a}x \right) + c \\ &= a \left(x^2 + \frac{b}{a}x + \frac{b^2}{4a^2} - \frac{b^2}{4a^2} \right) + c \\ &= a \left(x^2 + \frac{b}{a}x + \frac{b^2}{4a^2} \right) + a \left(-\frac{b^2}{4a^2} \right) + c \\ &= a \underbrace{\left(x^2 + \frac{b}{a}x + \frac{b^2}{4a^2} \right)}_{\text{This is } \left(x + \frac{b}{2a} \right)^2} + \underbrace{c - \frac{b^2}{4a}}_{\text{Call this part } C}. \\ &= au^2 + C \quad (u = x + (b/2a)) \end{aligned}$$

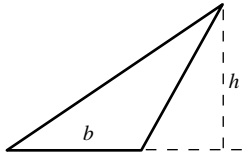
7. The Quadratic Formula If $a \neq 0$,

$$\begin{aligned} ax^2 + bx + c &= 0 \\ x &= \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}. \end{aligned}$$

Geometry

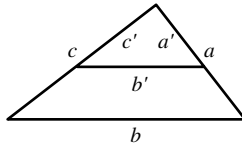
(A = area, B = area of base, C = circumference, S = lateral area or surface area, V = volume)

1. Triangle



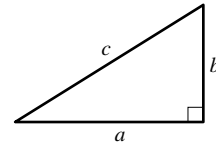
$$A = \frac{1}{2}bh$$

2. Similar Triangles



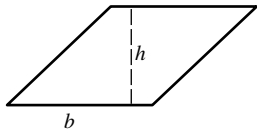
$$\frac{a'}{a} = \frac{b'}{b} = \frac{c'}{c}$$

3. Pythagorean Theorem



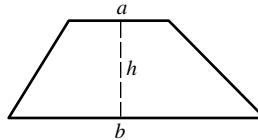
$$a^2 + b^2 = c^2$$

4. Parallelogram



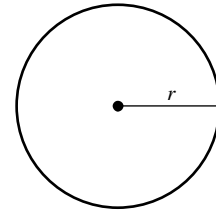
$$A = bh$$

5. Trapezoid



$$A = \frac{1}{2}(a + b)h$$

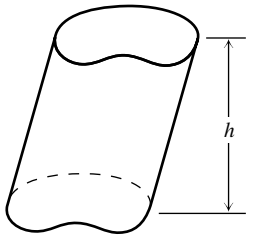
6. Circle



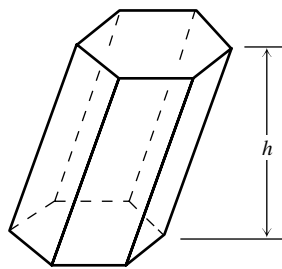
$$A = \pi r^2,$$

$$C = 2\pi r$$

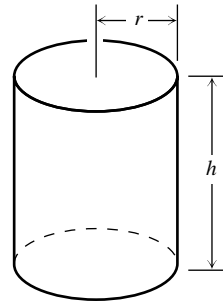
7. Any Cylinder or Prism with Parallel Bases



$$V = Bh$$

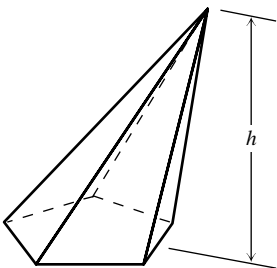


8. Right Circular Cylinder

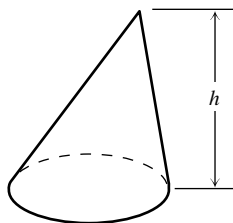


$$V = \pi r^2 h, S = 2\pi r h$$

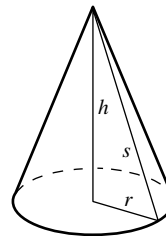
9. Any Cone or Pyramid



$$V = \frac{1}{3}Bh$$

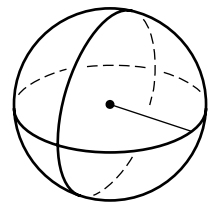


10. Right Circular Cone



$$V = \frac{1}{3}\pi r^2 h, S = \pi r s$$

11. Sphere

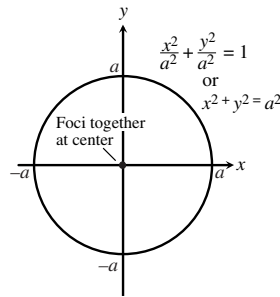
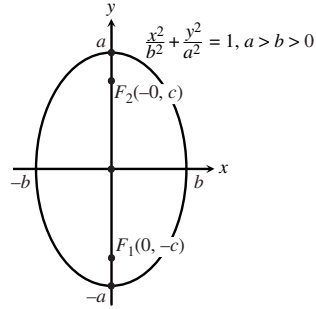
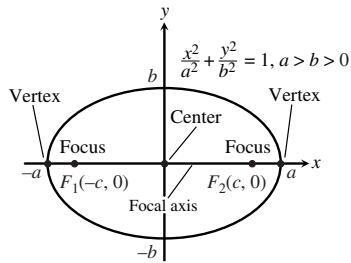


$$V = \frac{4}{3}\pi r^3, S = 4\pi r^2$$

Conic Sections

A **circle** is the set of points in a plane whose distance from a fixed point in the plane is constant. The fixed point is the **center** of the circle; the constant distance is the **radius**. An **ellipse** is the set of points in a plane whose distances from two fixed points in the plane have a constant sum. A **hyperbola** is the set of points in a plane whose distances from two fixed points in the plane have a constant difference. In each case, the fixed points are the **foci** of the conic section. A **parabola** is the set of points in a plane equidistant from a given fixed point and a given fixed line in the plane. The fixed point is the **focus** of the parabola; the line is the **directrix**.

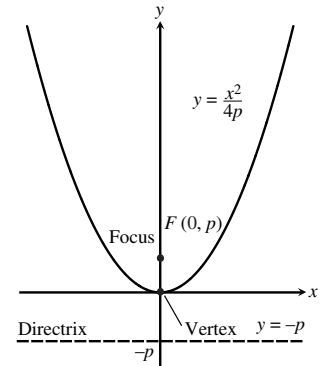
Ellipses and Circle in Standard Position



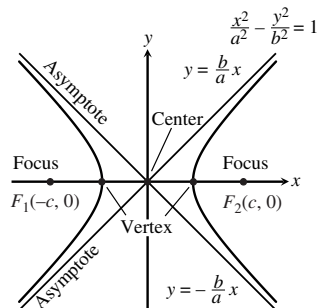
Degenerate case:
circle of radius a

For both ellipses:
 a = semimajor axis
 b = semiminor axis
 $c = \sqrt{a^2 - b^2}$ = center-to-focus distance
 Eccentricity: $e = c/a$, $0 < e < 1$

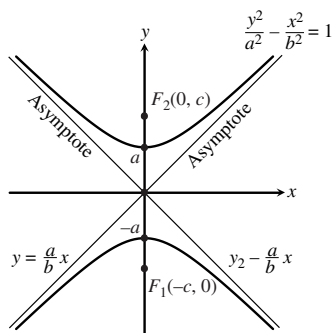
Parabolas in Standard Position



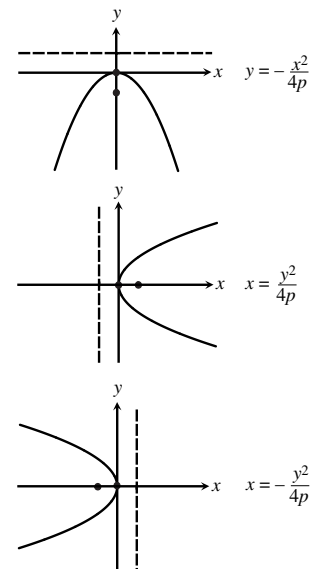
Hyperbolas in Standard Position



c = center-to-focus distance = $\sqrt{a^2 + b^2}$
 Eccentricity: $e = c/a > 1$
 Asymptotes: $y = \pm(b/a)x$



c = center-to-focus distance = $\sqrt{a^2 + b^2}$
 Eccentricity: $e = c/a > 1$
 Asymptotes: $y = \pm(a/b)x$



All parabolas have eccentricity $e = 1$

Vector Operator Formulas in Cartesian, Cylindrical, and Spherical Coordinates; Vector Identities

Formulas for Grad, Div, Curl, and the Laplacian

	Cartesian (x, y, z) $\mathbf{i}, \mathbf{j},$ and \mathbf{k} are unit vectors in the directions of increasing $x, y,$ and z . $F_x, F_y,$ and F_z are the scalar components of $\mathbf{F}(x, y, z)$ in these directions.	Cylindrical (r, θ, z) $\mathbf{u}_r, \mathbf{u}_\theta,$ and \mathbf{k} are unit vectors in the directions of increasing $r, \theta,$ and z . $F_r, F_\theta,$ and F_z are the scalar components of $\mathbf{F}(r, \theta, z)$ in these directions.	Spherical (ρ, ϕ, θ) $\mathbf{u}_\rho, \mathbf{u}_\phi,$ and \mathbf{u}_θ are unit vectors in the directions of increasing $\rho, \phi,$ and θ . $F_\rho, F_\phi,$ and F_θ are the scalar components of $\mathbf{F}(\rho, \phi, \theta)$ in these directions.
Gradient	$\nabla f = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k}$	$\nabla f = \frac{\partial f}{\partial r} \mathbf{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \mathbf{u}_\theta + \frac{\partial f}{\partial z} \mathbf{k}$	$\nabla f = \frac{\partial f}{\partial \rho} \mathbf{u}_\rho + \frac{1}{\rho} \frac{\partial f}{\partial \phi} \mathbf{u}_\phi + \frac{1}{\rho \sin \phi} \frac{\partial f}{\partial \theta} \mathbf{u}_\theta$
Divergence	$\nabla \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$	$\nabla \cdot \mathbf{F} = \frac{1}{r} \frac{\partial}{\partial r} (rF_r) + \frac{1}{r} \frac{\partial F_\theta}{\partial \theta} + \frac{\partial F_z}{\partial z}$	$\nabla \cdot \mathbf{F} = \frac{1}{\rho^2} \frac{\partial}{\partial \rho} (\rho^2 F_\rho)$ $+ \frac{1}{\rho \sin \phi} \frac{\partial}{\partial \phi} (F_\phi \sin \phi) + \frac{1}{\rho \sin \phi} \frac{\partial F_\theta}{\partial \theta}$
Curl	$\nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix}$	$\nabla \times \mathbf{F} = \begin{vmatrix} \frac{1}{r} \mathbf{u}_r & \mathbf{u}_\theta & \frac{1}{r} \mathbf{k} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ F_r & F_\theta & F_z \end{vmatrix}$	$\nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{u}_\rho & \mathbf{u}_\phi & \mathbf{u}_\theta \\ \rho^2 \sin \phi & \rho \sin \phi & \rho \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial \theta} \\ F_\rho & \rho F_\phi & \rho \sin \phi F_\theta \end{vmatrix}$
Laplacian	$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$	$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}$	$\nabla^2 f = \frac{1}{\rho^2} \frac{\partial}{\partial \rho} \left(\rho^2 \frac{\partial f}{\partial \rho} \right)$ $+ \frac{1}{\rho^2 \sin \phi} \frac{\partial}{\partial \phi} \left(\sin \phi \frac{\partial f}{\partial \phi} \right) + \frac{1}{\rho^2 \sin^2 \phi} \frac{\partial^2 f}{\partial \theta^2}$

Vector Triple Products

$$(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w} = (\mathbf{v} \times \mathbf{w}) \cdot \mathbf{u} = (\mathbf{w} \times \mathbf{u}) \cdot \mathbf{v}$$

$$\mathbf{u} \times (\mathbf{v} \times \mathbf{w}) = (\mathbf{u} \cdot \mathbf{w})\mathbf{v} - (\mathbf{u} \cdot \mathbf{v})\mathbf{w}$$

Vector Identities for the Cartesian Form of the Operator ∇

In the identities listed here, $f(x, y, z)$ and $g(x, y, z)$ are differentiable scalar functions and $\mathbf{u}(x, y, z)$ and $\mathbf{v}(x, y, z)$ are differentiable vector functions.

$$\nabla \cdot f\mathbf{v} = f\nabla \cdot \mathbf{v} + \mathbf{v} \cdot \nabla f = f\nabla \cdot \mathbf{v} + (\mathbf{v} \cdot \nabla)f$$

$$\nabla \times f\mathbf{v} - f\nabla \times \mathbf{v} + \nabla f \times \mathbf{v}$$

$$\nabla \cdot (\nabla \times \mathbf{v}) = 0$$

$$\nabla \times (\nabla f) = \mathbf{0}$$

$$\nabla(fg) = f\nabla g + g\nabla f$$

$$\nabla(\mathbf{u} \cdot \mathbf{v}) = (\mathbf{u} \cdot \nabla)\mathbf{v} + (\mathbf{v} \cdot \nabla)\mathbf{u} + \mathbf{u} \times (\nabla \times \mathbf{v}) + \mathbf{v} \times (\nabla \times \mathbf{u})$$

$$\nabla \cdot (\mathbf{u} \times \mathbf{v}) = \mathbf{v} \cdot (\nabla \times \mathbf{u}) - \mathbf{u} \cdot (\nabla \times \mathbf{v})$$

$$\nabla \times (\mathbf{u} \times \mathbf{v}) = (\mathbf{v} \cdot \nabla)\mathbf{u} - (\mathbf{u} \cdot \nabla)\mathbf{v} + \mathbf{u}(\nabla \cdot \mathbf{v}) - \mathbf{v}(\nabla \cdot \mathbf{u})$$

$$\nabla \times (\nabla \times \mathbf{v}) = \nabla(\nabla \cdot \mathbf{v}) - (\nabla \cdot \nabla)\mathbf{v} = \nabla(\nabla \cdot \mathbf{v}) - \nabla^2 \mathbf{v}$$

$$(\nabla \times \mathbf{v}) \times \mathbf{v} = (\mathbf{v} \cdot \nabla)\mathbf{v} - \frac{1}{2} \nabla(\mathbf{v} \cdot \mathbf{v})$$

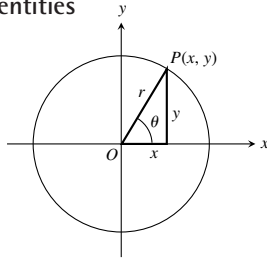
Trigonometry Formulas

1. Definitions and Fundamental Identities

Sine: $\sin \theta = \frac{y}{r} = \frac{1}{\csc \theta}$

Cosine: $\cos \theta = \frac{x}{r} = \frac{1}{\sec \theta}$

Tangent: $\tan \theta = \frac{y}{x} = \frac{1}{\cot \theta}$



2. Identities

$\sin(-\theta) = -\sin \theta, \quad \cos(-\theta) = \cos \theta$

$\sin^2 \theta + \cos^2 \theta = 1, \quad \sec^2 \theta = 1 + \tan^2 \theta, \quad \csc^2 \theta = 1 + \cot^2 \theta$

$\sin 2\theta = 2 \sin \theta \cos \theta, \quad \cos 2\theta = \cos^2 \theta - \sin^2 \theta$

$\cos^2 \theta = \frac{1 + \cos 2\theta}{2}, \quad \sin^2 \theta = \frac{1 - \cos 2\theta}{2}$

$\sin(A + B) = \sin A \cos B + \cos A \sin B$

$\sin(A - B) = \sin A \cos B - \cos A \sin B$

$\cos(A + B) = \cos A \cos B - \sin A \sin B$

$\cos(A - B) = \cos A \cos B + \sin A \sin B$

$\tan(A + B) = \frac{\tan A + \tan B}{1 - \tan A \tan B}$

$\tan(A - B) = \frac{\tan A - \tan B}{1 + \tan A \tan B}$

$\sin\left(A - \frac{\pi}{2}\right) = -\cos A, \quad \cos\left(A - \frac{\pi}{2}\right) = \sin A$

$\sin\left(A + \frac{\pi}{2}\right) = \cos A, \quad \cos\left(A + \frac{\pi}{2}\right) = -\sin A$

$\sin A \sin B = \frac{1}{2} \cos(A - B) - \frac{1}{2} \cos(A + B)$

$\cos A \cos B = \frac{1}{2} \cos(A - B) + \frac{1}{2} \cos(A + B)$

$\sin A \cos B = \frac{1}{2} \sin(A - B) + \frac{1}{2} \sin(A + B)$

$\sin A + \sin B = 2 \sin \frac{1}{2}(A + B) \cos \frac{1}{2}(A - B)$

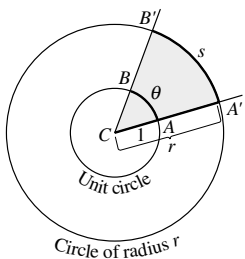
$\sin A - \sin B = 2 \cos \frac{1}{2}(A + B) \sin \frac{1}{2}(A - B)$

$\cos A + \cos B = 2 \cos \frac{1}{2}(A + B) \cos \frac{1}{2}(A - B)$

$\cos A - \cos B = -2 \sin \frac{1}{2}(A + B) \sin \frac{1}{2}(A - B)$

Trigonometric Functions

Radian Measure

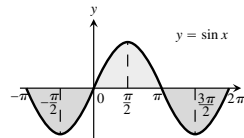


$\frac{s}{r} = \frac{\theta}{1} = \theta \quad \text{or} \quad \theta = \frac{s}{r}$

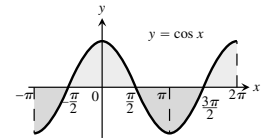
$180^\circ = \pi \text{ radians.}$

Degrees	Radians

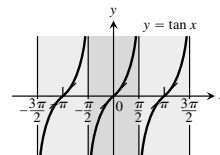
The angles of two common triangles, in degrees and radians.



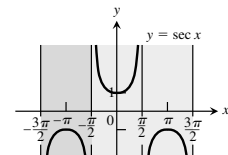
Domain: $(-\infty, \infty)$
Range: $[-1, 1]$



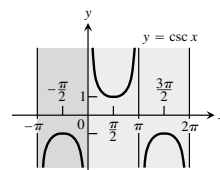
Domain: $(-\infty, \infty)$
Range: $[-1, 1]$



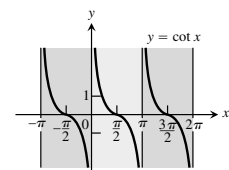
Domain: All real numbers except odd integer multiples of $\pi/2$
Range: $(-\infty, \infty)$



Domain: $x \neq \pm \frac{\pi}{2}, \pm \frac{3\pi}{2}, \dots$
Range: $(-\infty, -1] \cup [1, \infty)$



Domain: $x \neq 0, \pm \pi, \pm 2\pi, \dots$
Range: $(-\infty, -1] \cup [1, \infty)$



Domain: $x \neq 0, \pm \pi, \pm 2\pi, \dots$
Range: $(-\infty, \infty)$